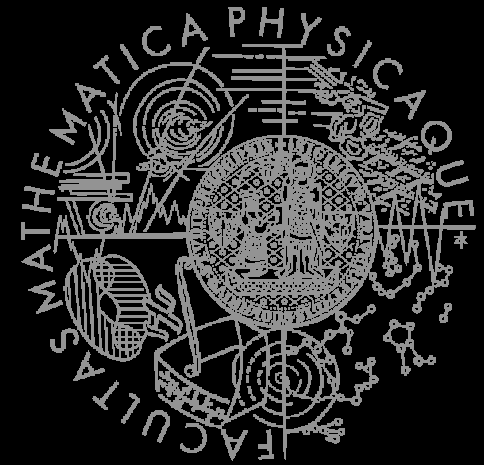


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10th March 2010

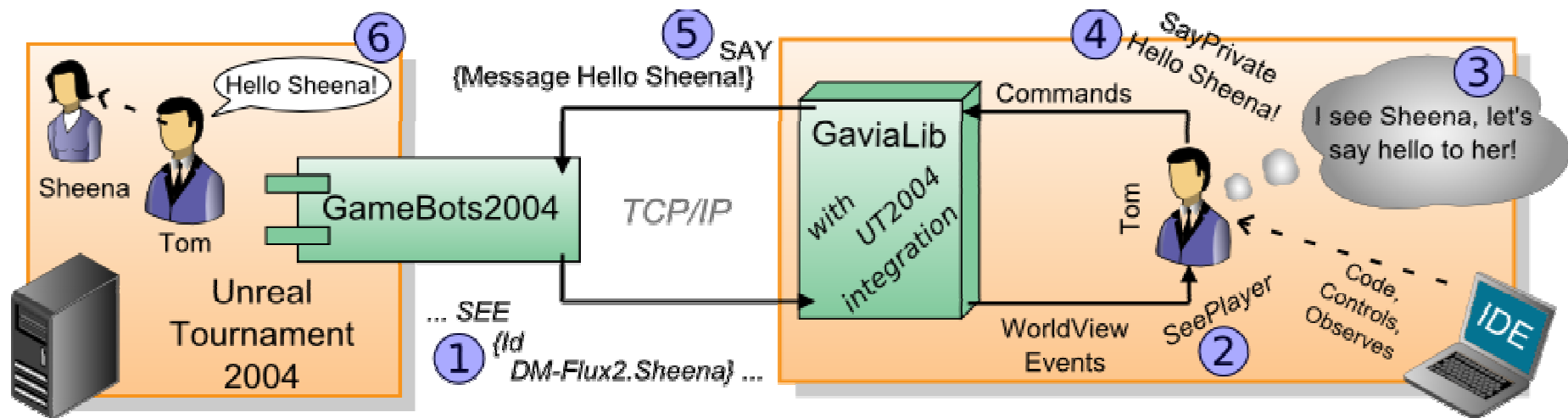


UT2004 bots made easy!

Pogamut 3

Lecture 3 – Senso/Motoric modules

Pogamut 3's agent



ItemPicker

How many of you have tried? 😊

<http://diana.ms.mff.cuni.cz/pogamut-devel>

There is going to be an example of ItemPicker...

Let's check it through! And extended its
functionality to do the 3rd homework...

Modules – Sensoric / Utility

- Sensoric
 - Game `new Game(bot);`
 - AgentInfo `new AgentInfo(bot, game);`
 - Players `new Players(bot, agent);`
 - Senses `new Senses(bot, agent, players);`
 - Items `new Items(bot, agent);`
 - AdvancedItems *... more complicated ...*
- Utility
 - TabuSet `new TabuSet<Item>(bot);`

Modules – Path planning/executing

- Path planning
 - `PathPlanner<ILocated, ILocated>`
 - UTStar
 - `new UTStar(bot);`
 - FloydWarshallPathPlanner
 - `new FloydWarshallPathPlanner(bot)`
- Path executing
 - `SimplePathExecutor<ILocated, ILocated>`
 - UTPathExecutor
 - `new UTPathExecutor(bot);`
 - Path event model
- *Good starting point – samples 02-NavigationBot*

Modules - Commands

- Commands

- CompleteBotCommandsWrapper

- `new CompleteBotCommandsWrapper(bot, getLog());`
 - Contains many submodules
 - You will need `module.getCommunication()`
 - And `module.getSimpleShooting()`
 - For the homework

Homework 3 – Retaliator bot

- Create a combination of item-picker + follow bot + simple retaliation with shooting
 1. bot is trying to pick all weapons in the map
 2. if it sees a player, it runs to him, stops around 200 units before him and than says "Hello <name>!"
 3. if the player shoot him, it will freak out and shout and retaliate for 3-4 ticks of the logic
 4. if the player is not moving for 2 secs, it will says "Good bye!" and return to item picking
 5. if bot's health is low (<50) it will search for health packs

Homework 2 - ItemPicker

- Create Item picker
- Ignore the knowledge of items
 - `getWorldView().getAll(Item.class)`
- Use `getWorldView()` and use `getAllVisible(Item.class)`
- Try to run around the whole level and discover (almost) all items
- How to know that your bot has visited almost everything?

Homework 1 – PathFollower

- Install Pogamut3
- Create a simple bot that is able to run randomly around navpoints
- You have to read about
 - command `GetPath()`
 - Class `Path()`
- Listeners
 - Weak references! Store pointers!