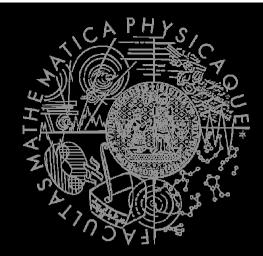
Faculty of mathematics and physics Charles University at Prague 10th March 2010

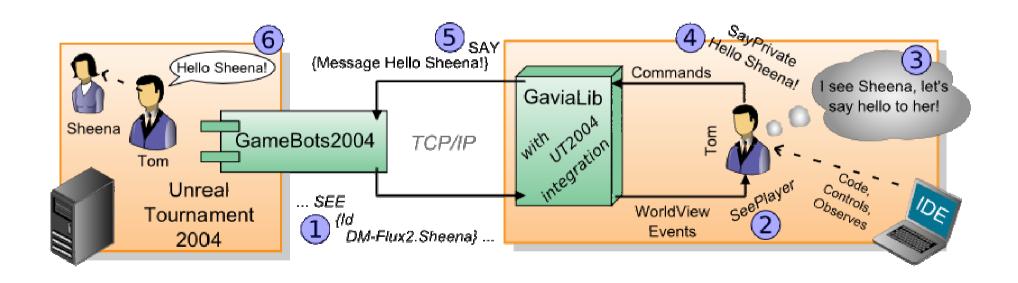


UT2004 bots made easy!

Pogamut 3

Lecture 4 – Senso/Motoric modules revisited

Pogamut 3's agent



Modules

Sensoric

TabuSet

```
 Game new Game(bot);
 AgentInfo new AgentInfo(bot, game);
 Players new Players(bot, agent);
 Senses new Senses(bot, agent, players);
 Items new Items(bot, agent);
 AdvancedItems ... more complicated ...
 Utility
```

new TabuSet<Item>(bot);

- Will be renamed to TabooSet... soon...

Modules

- Path planning
 - PathPlanner<ILocated, ILocated>
 - UTAstar
 - new UTAstar(bot);
 - FloydWarshallPathPlanner
 - new FloydWarshallPathPlanner(bot)
- Path executing
 - SimplePathExecutor<ILocated, ILocated>
 - UTPathExecutor
 - new UTPathExecutor(bot);
 - Path event model

Modules

```
Motoric
```

```
 Game new Game(bot);
 AgentInfo new AgentInfo(bot, game);
 Players new Players(bot, agent);
 Senses new Senses(bot, agent, players);
 Items new Items(bot, agent);
 AdvancedItems ... more complicated ...
 Utility
 TabuSet new TabuSet<Item>(bot);
```

Homework 4 – Simple CTF

- Create simple CTF bot (really simple!)
- Check out FlagInfo object
- Check out Initialize command for teambalancing
- 3. CTF rules
 - 1. You scores by stealing the flag
 - 2. You can't score if your flag is stolen
- 4. Play 2v2 or 3v3 (otherwise GB2004 might be unstable)

Homework 3 – Retaliator bot

- Create a combination of item-picker + follow bot
 + simple retaliation with shooting
- 1. bot is trying to pick all weapons in the map
- if it sees a player, it runs to him, stops around 200 units before him and than says "Hello <name>!"
- 3. if the player shoot him, it will freak out and retaliate for 3-4 ticks of the logic
- 4. if the player is not moving for 2 secs, it will says "Good bye!" and return to item picking
- 5. if bot's health is low (<50) it will search for health packs

Homework 2 - ItemPicker

- Create Item picker
- Ignore the knowledge of items
 - getWorldView().getAll(Item.class)
- Use getWorldView() and use getAllVisible(Item.class)
- Try to run around the whole level and discover (almost) all items
- How to know that your bot has visited almost everything?

Homework 1 - PathFollower

- Install Pogamut3
- Create a simple bot that is able to run randomly around navpoints
- You have to read about
 - command GetPath()
 - Class Path()
- Listeners
 - Weak references! Store pointers!