

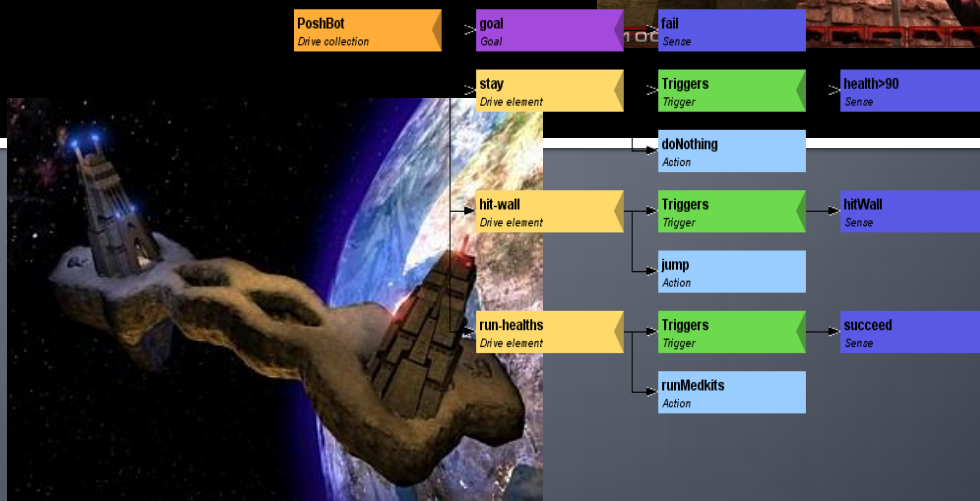
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5<sup>nd</sup> May 2014



UT2004 bots made easy!

# Pogamut 3

Lecture 09 – CTF



# Warm Up!



- Fill the short test for this lessons
  - 6 minutes limit
  - <http://alturl.com/p5su7>
  - [https://docs.google.com/forms/d/1kgyKJXq2x-yyx2GpLmTk\\_pgOAMpSipBXTVjbXFuo8as/viewform](https://docs.google.com/forms/d/1kgyKJXq2x-yyx2GpLmTk_pgOAMpSipBXTVjbXFuo8as/viewform)

# Today's menu



## 1. Tips

- Navigation
- yaPOSH

## 2. Capture the Flag (CTF)

# Tips

## Useful classes



- **MyCollections**

```
Item targetItem = MyCollections.getRandomFiltered(  
    items.getSpawnedItems(UT2004ItemType.Category.  
        WEAPON), myIFilter  
);
```

- **fwMap**

```
fwMap.getNearestFilteredItem(...)
```

- **DistanceUtils**

- **Heatup**

- **Cooldown**

# Tips

## Anti-stuck I



- **Always handle STUCK event!**
  - Use TabooSets to temporarily filter items/navpoints you were stuck going to
    - This prevents your bot to cycle in 1) pick the same item, 2) run towards it, 3) stuck

```
TabooSet<Item> tabooItems = new TabooSet<Item>(bot);
this.navigation.addStrongNavigationListener(

    new FlagListener<NavigationState>() {
        @Override
        public void flagChanged(NavigationState changedValue) {
            switch (changedValue) {
                case STUCK:
                case PATH_COMPUTATION_FAILED:
                    tabooItems.add(targetItem, 30);
                break;
            }
        }
    }
);
```

# Tips

## Anti-stuck II



- Then don't forget to use your taboo set to filter the items you are picking from!

```
if (!this.navigation.isNavigating()) {  
    targetItem = MyCollections.getRandom(  
        tabooItems.filter(items.getSpawnedItems().values())  
    );  
    this.navigation.navigate(targetItem);  
}
```

# Tips

## aStar – plugging the path to navigation



1. Get starting point

```
NavPoint from =  
    navigation.getNearestNavPoint(  
        info.getLocation()  
    );
```

2. Get target point

```
NavPoint to =  
    MyCollections.getRandom(  
        navPoints.getNavPoints().values()  
    );
```

3. Find the path

```
IPathFuture pf =  
    aStar.computePath(from, to);
```

4. Execute it

```
this.navigation.navigate(pf);
```

# Tips

## yaPOSH – setting up stuff



- In yaPOSH, a good place to register navigation state listeners, TabooSets and weapon preferences is in the constructor of bot context class, e.g.:

```
public AttackBotContext(UT2004Bot bot) {  
    super("AttackBotContext", bot);  
    // IMPORTANT: Various modules of context must be initialized.  
    initialize();  
  
    // INITIALIZE CUSTOM MODULES  
    getWeaponPrefs()...;  
    ...  
}
```

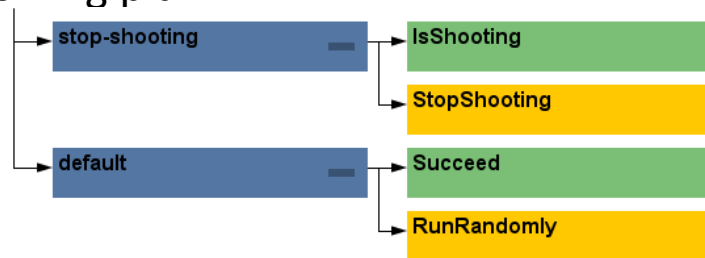


# Tips

## yaPOSH – ActionResult.FINISHED



- Action returning **ActionResult.FINISHED** in **run()** method tells POSH to re-evaluate plan immediately to search for a new action
- This can be used to your advantage (parallel actions), but has a caveat!
- Consider plan, where **StopShooting** returns **ActionResult.FINISHED** in run method in following plan:



- Makes sense, because as we send stop shoot command in **init()**, the action is done...
- The problem is that the POSH re-evaluates the plan immediately to search for a new action and guess what it finds? **StopShooting** again. Why?
  - Because isShooting sense will be returning the same value it was before! The environmental state is not changed. The POSH re-evaluates immediately! We are stuck in infinite loop and no more environmental updates will ever come (even at first glance no exceptions raised).
- For these types of actions always return **RUNNING\_ONCE** !
- And in general – **ActionResult.FINISHED** is tricky, use it only when you know why are you doing it

# Today's menu



1. Tips
  - Navigation
  - yaPOSH
2. **Capture the Flag (CTF)**

# Capture the Flag (CTF)

## Rules



- Players/bots are divided into two teams (red and blue).
- Each team has a flag in his base.
- The goal of the team is to capture the flag of the opposite team and bring it to their home base.
- When managed, the team scores 1 point.
  - Team can only bring opposite flag home and score a point, if the team flag is in team home base!
- If the flag is dropped it will be returned to home base after some time.



# Pogamut CTF support

## Bases & game status



- **CTF module**
  - `this.ctf`
- **Where are the bases?**
  - `this.ctf.getOurBase();`
  - `this.ctf.getEnemyBase();`
- **Whats the game status?**
  - `this.ctf.canOurTeamScore();`
  - `this.ctf.canEnemyTeamScore();`
- **Am I winning?**
  - `game.getTeamScores();`
  - `info.getTeamScore();`

# Pogamut CTF support II

## Flags



- **I want my flag!**
  - Flag is represented by **FlagInfo** object.
  - `this.ctf.getOurFlag();`
  - `this.ctf.getEnemyFlag();`
- **Is someone messing with my flag?**
  - `this.ctf.isOurFlagHome();`
  - `this.ctf.isOurFlagHeld();`
- **How about enemy flag?**
  - `this.ctf.isEnemyFlagHome();`
  - `this.ctf.isEnemyFlagHeld();`

# Pogamut CTF support III

## Team communication



- Use **SendMessage** command.

```
this.act.act(  
    new SendMessage()  
  
        .setTeamIndex(info.getTeam()) .setText("Help  
")  
);
```

- Listen to team message with **TeamChat** event.

```
@EventListener(eventClass = TeamChat.class)  
public void teamChat(TeamChat event) {  
    ...  
}
```

- OLD AND SLOW

# Pogamut CTF support IV

## UT2004TeamComm 1/3



- Allows you to send Serializable Java objects between members of the team
- Allows you to specify “subchannels”
- You can easily listens to your messages as if they were `IWorldEvent` objects

# Pogamut CTF support IV

## UT2004TeamComm 2/3



```
@EventListener(eventClass=TCMessage.class)
public void allMsg(TCMessage tcMessage) {
    log.info("@EventListener(TCMessage)");
}
```

```
@EventListener(eventClass=TCHello.class)
public void hello(TCHello hello) {
    log.info("@EventListener(TCHello)");
}
```



# Pogamut CTF support IV

## UT2004TeamComm 3/3



```
public class TeamCommBot extends  
    UT2004BotTCController<UT2004Bot>
```

```
<dependencies>  
  <dependency>  
    <groupId>cz.cuni.amis.pogamut.ut2004</groupId>  
    <artifactId>ut2004-team-comm</artifactId>  
    <version>3.6.1-SNAPSHOT</version>  
  </dependency>  
</dependencies>
```

Example available at:

- <svn://artemis.ms.mff.cuni.cz/pogamut/trunk/project/Main/PogamutUT2004Examples/26-TeamCommBot>

# Assignment

(on Lecture)



- Create **CTFBot** in **yaPOSH**
  - Arm yourself before going into action!
  - Try to get enemy flag!
  - Try to get your flag, if it is stolen!

# Assignment

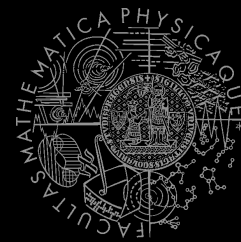
## Cheatsheet



- **Locations of interest**
  - `this.ctf.getOurBase();`
  - `this.ctf.getEnemyBase();`
- **Useful info about the game (could be senses)**
  - `this.ctf.canOurTeamScore();`
  - `this.ctf.canEnemyTeamScore();`
  - `this.ctf.isEnemyFlagHome();`
  - `this.ctf.isOurFlagHeld();`
  - `this.ctf.isBotCarryingEnemyFlag();`
    - Our bot
- **Flag is represented by FlagInfo object**
  - `this.ctf.getOurFlag();`
    - Can check `isVisible()`...

# Questions?

I sense a soul in search of answers...



- We do not own the patent of perfection (yet...)
- In case of doubts about the assignment, tournament or hard problems, bugs don't hesitate to contact us!
  - Jakub Gemrot (Tuesday practice lessons)
    - [jakub.gemrot@gmail.com](mailto:jakub.gemrot@gmail.com)
  - Michal Bída (Monday practice lessons)
    - [michal.bida@gmail.com](mailto:michal.bida@gmail.com)