## Example 1: Basic watering

garden\_watered not\_hold\_any\_can can\_in\_hands can empty know\_about\_dry\_bed not\_stand\_nextTo\_theBed theBed\_dry 1. if garden watered and cleaned then COMMIT 2. if garden watered then subGoal Clean if not\_hold\_any\_can then subGoal\_FindTakeCan

4. if can\_in\_hands and empty then subGoal\_FillUpTheCan

5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed then subGoal\_GoThere

6. if stand nextTo theBed and theBed dry then atomicWatering

Clean

App.

Taxi

garden\_watered not\_hold\_any\_can can\_in\_hands can empty know\_about\_dry\_bed not\_stand\_nextTo\_theBed theBed\_dry 1. if garden watered and cleaned then COMMIT 2. if garden watered then subGoal Clean

if not\_hold\_any\_can then subGoal\_FindTakeCan

4. if can\_in\_hands and empty then subGoal\_FillUpTheCan

5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed then subGoal\_GoThere

6. if stand nextTo theBed and theBed dry then atomicWatering

Clean

App.

Taxi

garden\_watered not\_hold\_any\_can can\_in\_hands can\_empty know\_about\_dry\_bed not\_stand\_nextTo\_theBed theBed\_dry 1. if garden watered and cleaned then COMMIT 2. if garden watered then subGoal Clean

3. if not\_hold\_any\_can then subGoal\_FindTakeCan

4. if can\_in\_hands and empty then subGoal\_FillUpTheCan

5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed then subGoal\_GoThere

6. if stand\_nextTo\_theBed and theBed\_dry then atomicWatering

Clean

App.

Taxi

garden\_watered not\_hold\_any\_can can\_in\_hands can empty know\_about\_dry\_bed not\_stand\_nextTo\_theBed theBed\_dry 1. if garden watered and cleaned then COMMIT 2. if garden watered then subGoal Clean

3. if not\_hold\_any\_can then subGoal\_FindTakeCan

4. if can\_in\_hands and empty then subGoal\_FillUpTheCan

5. if know about dry bed & not stand nextTo theBed then subGoal\_GoThere

if stand\_nextTo\_theBed and theBed\_dry then atomicWatering

App.

Clean

Taxi

garden\_watered not\_hold\_any\_can can\_in\_hands can\_empty not\_stand\_nextTo\_theBed know\_about\_dry\_bed theBed\_dry 1. if garden watered and cleaned then COMMIT 2. if garden watered then subGoal Clean 3. if not\_hold\_any\_can then subGoal\_FindTakeCan 4. if can\_in\_hands and empty then subGoal\_FillUpTheCan

5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed then subGoal\_GoThere

**6. if** stand\_nextTo\_theBed and theBed\_dry **then** atomicWatering

Taxi

App.

Clean

garden\_watered not\_hold\_any\_can can\_in\_hands can\_empty not\_stand\_nextTo\_theBed know\_about\_dry\_bed theBed\_dry 1. if garden watered and cleaned then COMMIT 2. if garden watered then subGoal Clean

3. if not hold any can then subGoal FindTakeCan

4. if can\_in\_hands and empty then subGoal\_FillUpTheCan

5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed then subGoal\_GoThere

6. if stand\_nextTo\_theBed and theBed\_dry then atomicWatering

App.

Clean

Taxi

## Example 2: Filling the watering can

```
garden_watered
 not_hold_any_can
                                 can_in_hands
                                  can_empty
know_about_dry_bed
                            not_stand_nextTo_theBed
                                  theBed_dry
```

- 1. if garden watered and cleaned then COMMIT
- 2. if garden watered then subGoal Clean
- 3. if not\_hold\_any\_can then subGoal\_FindTakeCan
- 4. if can\_in\_hands and empty then subGoal\_FillUpTheCan
- 5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed then subGoal\_GoThere
- 6. if stand nextTo theBed and theBed dry then atomicWatering

garden\_watered

not\_hold\_any\_can
can\_in\_hands

\_\_\_\_can\_empty

know\_about\_dry\_bed
not\_stand\_nextTo\_theBed

theBed\_dry

- 1. if garden\_watered and cleaned then COMMIT
- 2. if garden\_watered then subGoal\_Clean
- 3. if not\_hold\_any\_can then subGoal\_FindTakeCan
- 4. if can\_in\_hands and empty then subGoal\_FillUpTheCan
- 5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed
   then subGoal\_GoThere
- 6. if stand\_nextTo\_theBed and theBed\_dry then atomicWatering

garden\_watered not\_hold\_any\_can can\_in\_hands can\_empty know\_about\_dry\_bed not\_stand\_nextTo\_theBed theBed\_dry

- 1. if garden watered and cleaned then COMMIT
- 2. if garden watered then subGoal Clean
- 3. if not\_hold\_any\_can then subGoal\_FindTakeCan
- 4. if can\_in\_hands and empty then subGoal\_FillUpTheCan
- 5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed then subGoal\_GoThere
- 6. if stand\_nextTo\_theBed and theBed\_dry then atomicWatering

## Example 3: More watering cans

#### Example 4: More objects in general

- 1. if garden\_finished and cleaned then COMMIT
- 2. if garden\_finished then subGoal\_Clean
- 3. if not\_hold\_any\_bucket then subGoal\_FindTakeBucket
- 4. ...

- 1. if garden\_finished and cleaned then COMMIT
- 2. if garden\_finished then subGoal\_Clean
- 3. if not\_hold\_any\_bucket then subGoal\_FindTakeBucket
- 4. if not\_have\_rake then subGoal\_PutRakeToBucket
- 5. ...

- 1. if garden\_finished and cleaned then COMMIT
- 2. if garden\_finished then subGoal\_Clean
- 3. if not\_hold\_any\_bucket then subGoal\_FindTakeBucket
- 4. if not\_have\_rake then subGoal\_PutRakeToBucket
- 5. if not\_have\_scoop then subGoal\_PutScoopToBucket
- 6. . . .

- 1. if garden\_finished and cleaned then COMMIT
- 2. if garden\_finished then subGoal\_Clean
- 3. if not\_hold\_any\_bucket then subGoal\_FindTakeBucket
- 4. if not\_have\_rake then subGoal\_PutRakeToBucket
- 5. if not\_have\_scoop then subGoal\_PutScoopToBucket
- 6. if not\_have\_plane then subGoal\_PutPlaneToBucket

7. . . .

#### Example 5: Timeouts

garden\_watered

not\_hold\_any\_can
can\_in\_hands

\_\_\_can\_empty\_\_\_\_

know\_about\_dry\_bed
not\_stand\_nextTo\_theBed

theBed\_dry

- 1. if garden\_watered and cleaned then COMMIT
- 2. if garden\_watered then subGoal\_Clean
- 3. if not\_hold\_any\_can then subGoal\_FindTakeCan
- 4. if can\_in\_hands and empty then subGoal\_FillUpTheCan
- 5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed
   then subGoal\_GoThere
- 6. if stand\_nextTo\_theBed and theBed\_dry then atomicWatering

Timeout = 15:00.00

### 14:55.00

#### 14:57.00

### 14:58.00

### 14:59.00

#### Example 6: The player

- 1. if garden\_watered and cleaned then COMMIT
- 2. if garden\_watered then subGoal\_Clean

Clean

- 3. if not\_hold\_any\_can then subGoal\_FindTakeCan
- 4. if can\_in\_hands and empty then subGoal\_FillUpTheCan

App.

5. if know\_about\_dry\_bed & not\_stand\_nextTo\_theBed
 then subGoal GoThere

Taxi

6. if stand\_nextTo\_theBed and theBed\_dry then
 atomicWatering