Faculty of mathematics and physics Charles University at Prague 25th March 2011



UT2004 bots made easy!

Pogamut 3

Lecture 5 – POSH



Warm up!

Fill the test for this lecture!

Home work: DeathMatch of two bots

Let's review home works from previous lectures!

Today's menu

1. Gentle POSH introduction

- Actions/Senses
- Drive collection/Competences/Action Patterns

2. Using POSH to implement a bot

POSH bot maven project archetype

POSH?

POSH

- Parallel-rooted, Ordered Slip-stack Hierarchical planner
- To put it simply:
 - a reactive planner working with FIXED, PRE-SET plans
- To put it simpler:
 - a tool enabling to specify if then rules with priority in a tree like structure

POSH - primitives

Actions and Senses

- if (sense) then (action)
- Drive Collection
 - First level of if-then rules
- Competence
 - Second Nth level of if-then rules
- Action Patterns
 - Specifies N actions that will be performed in a sequence

POSH plan structure

```
DriveCollection(
   1. if (sense) then competence1 return;
   2. if (sense) then competence2 return;
   3. if (sense) then action-pattern1 return;
   4. if (sense) then competence3 (
            1. if (sense) then action1 return;
            2. if (sense) then competence4 return;
            3. if (sense) then action2 return;
            4. if (sense) then action-pattern return;
            5. return;
ActionPattern(
   action1+return, action2+return, action3+return,
   action4+return
```

Competence vs Drive Collection?

- What's the difference?
- In interruptions:
 - When sense of higher drive collection element becomes active, the higher element takes control immediately.
 - When sense of higher element in competition becomes active, the lower element first finishes and only afterwards the higher sense takes control. (Hard-to-utilize, nested competences are rare.)
- Anyway, it's a bit fuzzy and it depends on POSH implementation...

POSH bot archetype

```
GroupId:
   cz.cuni.amis.pogamut.ut2004.examples
ArtifactId:
    o7-sposh-prey-bot-archetype
Version:
   3.2.1
Repository:
   http://diana.ms.mff.cuni.cz:8081/artifactory/repo
```

Assignment (or HomeWork)

- Create your own HunterBot in POSH!
 - Provide item collector behavior if needed
 - Provide simple combat behavior
 - 3. Try to balance priorities / parameters!
 - 4. Use DM-10n1-Albatross map

Send your assignments to

- Completely zip-up your project(s) folder
- Send it to:
 - Jakub Gemrot (Friday practice lessons)
 - jakub.gemrot@gmail.com
 - Michal Bída (Wednesday practice lessons)
 - michal.bida@gmail.com